Numerical Solutions for the Improved Korteweg De Vries and the Two Dimension Korteweg De Vries (2D Kdv) Equations

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GJSFR-F Classification : MSC 2010: 35Q53
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1. Introduction

The nonlinear partial differential equations (NPDEs) are widely used to describe many important phenomena and dynamic processes in physics, chemistry, biology, fluid dynamics, plasma, optical fibers and other areas of engineering. Many efforts have been made to study NPDEs. One of the most exciting advances of nonlinear science and theoretical physics has been a development of methods that look for exact solutions for nonlinear evolution equations. The availability of symbolic computations such as Mathematica, has popularized direct seeking for exact solutions of nonlinear equations. Therefore, exact solution methods of nonlinear evolution equations have become more and more important resulting in methods like the tanh method [1–3], extended tanh function method [4, 5], the modified extended tanh function method [6], the generalized hyperbolic function [7]. Most of exact solutions have been obtained by these methods, including the solitary wave solutions, shock wave solutions, periodic wave solutions, and the like. In this paper, we propose the extended \(\frac{G'(\xi)}{G(\xi)}\)-expansion method to find the exact solutions of the improved Korteweg de Vries (IKdV) equation and the two dimension Korteweg de Vries (2D KdV) equation. Our main goal in this study is to present the improved \(\frac{G'(\xi)}{G(\xi)}\)-expansion method [12-15] for constructing the travelling wave solutions. In section 2, we describe the \(\frac{G'(\xi)}{G(\xi)}\)-expansion method. In section 3, we apply the method to two physically important nonlinear evolution equations.

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II. OUTLINE OF THE $\left( \frac{G'(\xi)}{G(\xi)} \right)$-EXPANSION METHOD

The $\left( \frac{G'(\xi)}{G(\xi)} \right)$-expansion method will be introduced as presented by A. Hendi [8] and by [12–15]. The method is applied to find out an exact solution of a nonlinear ordinary differential equation. Consider the nonlinear partial differential equation in the form

$$N(u, u_t, u_x, u_{tx}, u_{xx}, ...) = 0 \quad (2.1)$$

Where $u(x, t)$ is the solution of nonlinear partial differential equation Eq. (1). We use the transformation, $\xi = (x - c t)$, to transform $u(x, t)$ to $u(\xi)$ give:

$$\frac{\partial}{\partial t} = -c \frac{d}{d\xi}, \quad \frac{\partial}{\partial x} = \frac{d}{d\xi}, \quad \frac{\partial^2}{\partial x^2} = \frac{d^2}{d\xi^2}, \quad \frac{\partial^3}{\partial x^3} = \frac{d^3}{d\xi^3}, \quad (2.2)$$

and so on, then Eq. (1) becomes an ordinary differential equation

$$N(u, -c u', u', c^2 u'', -c u'', ......) = 0, \quad (2.3)$$

The solution of Eq. (3) can be expressed by a polynomial in $\frac{G'(\xi)}{G(\xi)}$:

$$u(\xi) = \sum_{i=-N}^{N} a_i \left( \frac{G'(\xi)}{G(\xi)} \right)^i, \quad (2.4)$$

Where $G = G(\xi)$ satisfies,

$$G''(\xi) + \lambda G'(\xi) + \mu G(\xi) = 0, \quad (2.5)$$

Where $G'(\xi) = \frac{d G(\xi)}{d\xi}$, $G''(\xi) = \frac{d^2 G(\xi)}{d\xi^2}$, $\lambda$, and $\mu$ are constants to be determined later, $a_i \neq 0$, the unwritten part in (4) is also a polynomial in $\frac{G'(\xi)}{G(\xi)}$, but the degree of which is generally equal to or less than $m - 1$, the positive integer $m$ can be determined by balancing the highest order derivative terms with nonlinear term appearing in Eq. (3). The solutions of Eq. (5) for $\left( \frac{G'}{G} \right)$ can be written in the form of hyperbolic, trigonometric and rational functions as given below [8].

$$\frac{G'(\xi)}{G(\xi)} = \begin{cases} \frac{\sqrt{\lambda^2 - 4 \mu}}{2} \left( \frac{C_1 \sinh(\frac{\sqrt{\lambda^2 - 4 \mu}}{2} \xi) + C_2 \cosh(\frac{\sqrt{\lambda^2 - 4 \mu}}{2} \xi)}{\cosh(\frac{\sqrt{\lambda^2 - 4 \mu}}{2} \xi)} \right) - \frac{\lambda}{2}, & \text{when } \lambda^2 - 4 \mu > 0, \\ \frac{\sqrt{4 \mu - \lambda^2}}{2} \left( -\frac{C_1 \sin(\frac{4 \mu - \lambda^2}{2} \xi) + C_2 \cos(\frac{4 \mu - \lambda^2}{2} \xi)}{\cos(\frac{4 \mu - \lambda^2}{2} \xi)} \right) - \frac{\lambda}{2}, & \text{when } \lambda^2 - 4 \mu > 0, \\ \frac{C_2}{C_1 + C_2 \xi} = \frac{\lambda}{2}, & \text{when } \lambda^2 - 4 \mu = 0, \end{cases} \quad (2.6)$$

Where $C_1$ and $C_2$ are integration constants. Inserting Eq. (4) into (3) and using Eq. (5), collecting all terms with the same order $\frac{G'(\xi)}{G(\xi)}$ together, the left hand side of Eq. (3) is converted into another
polynomial in \( \frac{G'(\xi)}{G(\xi)} \). Equating each coefficients of this polynomial to zero, yields a set of algebraic equations for \( a_i, \lambda, \) and \( \mu \). With the knowledge of the coefficients \( a_i \) and general solution of Eq.(5) we have more travelling wave solutions of the nonlinear evolution Eq.(1).

### III. Applications

In order to illustrate the effectiveness of the proposed method, two examples in mathematical are chosen as follows

**a) The improved Korteweg de Vries (IKdV) equation**

We consider the IKdV equation in the form [11]

\[ u_t + \epsilon u u_x + \beta u_{xxx} - \delta u_{xxt} = 0, \tag{3.1} \]

We make the transformation

\[ u(x,t) = u(\xi), \xi = x - c t, \tag{3.2} \]

Eq. (3.1) becomes

\[ -c u' + \epsilon u u' + \beta u''' + \delta c u'' = 0, \tag{3.3} \]

Integrating the above equation with respect to \( \xi \), we get

\[ -c u + \frac{\epsilon}{2} u^2 + (\beta + \delta c) u'' = 0, \tag{3.4} \]

Balancing \( u^2 \) with \( u'' \) gives \( m = 2 \). Thus, we suppose solutions of Eq. (3.3) can be expressed by

\[ u(\xi) = a_0 + a_1 \left( \frac{G'(\xi)}{G(\xi)} \right) + a_2 \left( \frac{G'(\xi)}{G(\xi)} \right)^2, \tag{3.5} \]

Where \( a_0, a_1, a_2 \) are constants. Substituting Eq.(3.5) into Eq.(3.4), collecting the coefficients of \( \left( \frac{G'(\xi)}{G(\xi)} \right) \) we obtain a set of algebraic equations for \( a_0, a_1, a_2 \) and \( c \), and solving this system we obtain the two sets of solutions as

**Case (1)**

\[ a_0 = -\frac{2\beta(\lambda^2+2\mu)}{\epsilon(1+\delta(\lambda^2-4\mu))}, a_1 = -\frac{12\beta \lambda}{\epsilon(1+\delta(\lambda^2-4\mu))}, a_2 = -\frac{12\beta}{\epsilon(1+\delta(\lambda^2-4\mu))}, \text{ and } c = -\frac{\beta(\lambda^2-4\mu)}{1+\delta(\lambda^2-4\mu)}. \tag{3.6} \]

**Case (2)**

\[ a_0 = \frac{12\beta \mu}{\epsilon(-1+\delta(\lambda^2-4\mu))}, a_1 = \frac{12\beta \lambda}{\epsilon(-1+\delta(\lambda^2-4\mu))}, a_2 = \frac{12\beta}{\epsilon(-1+\delta(\lambda^2-4\mu))}, \text{ and } c = -\frac{\beta(\lambda^2-4\mu)}{-1+\delta(\lambda^2-4\mu)}. \tag{3.7} \]

By using Eq.(21), Eq.(20) can be written as

\[ u(\xi) = -\frac{2\beta(\lambda^2+2\mu)}{\epsilon(1+\delta(\lambda^2-4\mu))} - \frac{12\beta \lambda}{\epsilon(1+\delta(\lambda^2-4\mu))} \left( \frac{G'(\xi)}{G(\xi)} \right) - \frac{12\beta}{\epsilon(1+\delta(\lambda^2-4\mu))} \left( \frac{G'(\xi)}{G(\xi)} \right)^2, \tag{3.8} \]

or by using Eq.(3.7), Eq.(3.6) can be written as

\[ u(\xi) = \frac{12\beta \mu}{\epsilon(-1+\delta(\lambda^2-4\mu))} + \frac{12\beta \lambda}{\epsilon(-1+\delta(\lambda^2-4\mu))} \left( \frac{G'(\xi)}{G(\xi)} \right) + \frac{12\beta}{\epsilon(-1+\delta(\lambda^2-4\mu))} \left( \frac{G'(\xi)}{G(\xi)} \right)^2. \tag{3.9} \]

We have three types of travelling wave solutions of the IKdV equation as
The first type: when $\lambda^2 - 4 \mu > 0$,

$$u_1(\xi) = \left( \frac{3\beta(4\mu-\lambda^2)}{e(1+\delta(\lambda^2-4\mu))} \right) \left( \frac{C_1 \sinh(\frac{\lambda^2-4\mu}{2} \xi) + C_2 \cosh(\frac{\lambda^2-4\mu}{2} \xi)}{C_1 \cosh(\frac{\lambda^2-4\mu}{2} \xi) + C_2 \sinh(\frac{\lambda^2-4\mu}{2} \xi)} \right)^2 - \frac{1}{3}, \quad (3.10)$$

Where $\xi = x + \frac{\beta(\lambda^2-4\mu)}{1+\delta(\lambda^2-4\mu)} t$, or

$$u_2(\xi) = \left( \frac{3\beta(4\mu-\lambda^2)}{e(-1+\delta(\lambda^2-4\mu))} \right) \left( 1 - \frac{C_1 \sinh(\frac{\lambda^2-4\mu}{2} \xi) + C_2 \cosh(\frac{\lambda^2-4\mu}{2} \xi)}{C_1 \cosh(\frac{\lambda^2-4\mu}{2} \xi) + C_2 \sinh(\frac{\lambda^2-4\mu}{2} \xi)} \right)^2 \quad (3.11)$$

The second type: when $\lambda^2 - 4 \mu < 0$,

$$u_3(\xi) = \left( \frac{-3\beta(4\mu-\lambda^2)}{e(1+\delta(\lambda^2-4\mu))} \right) \left( \frac{-C_1 \sinh(\frac{4\mu-\lambda^2}{2} \xi) + C_2 \cosh(\frac{4\mu-\lambda^2}{2} \xi)}{C_1 \cosh(\frac{4\mu-\lambda^2}{2} \xi) + C_2 \sinh(\frac{4\mu-\lambda^2}{2} \xi)} \right)^2 + \frac{1}{3} \quad (3.12)$$

Where $\xi = x + \frac{\beta(\lambda^2-4\mu)}{1+\delta(\lambda^2-4\mu)} t$, or

$$u_4(\xi) = \left( \frac{3\beta(4\mu-\lambda^2)}{e(-1+\delta(\lambda^2-4\mu))} \right) \left( \frac{-C_1 \sinh(\frac{4\mu-\lambda^2}{2} \xi) + C_2 \cosh(\frac{4\mu-\lambda^2}{2} \xi)}{C_1 \cosh(\frac{4\mu-\lambda^2}{2} \xi) + C_2 \sinh(\frac{4\mu-\lambda^2}{2} \xi)} \right)^2 + 1 \quad (3.13)$$

The third type: when $\lambda^2 - 4 \mu = 0$

$$u_5(\xi) = \frac{-12\beta}{e} \left( \frac{C_2}{C_1 + C_2 \xi} \right)^2, \quad \text{Where} \quad \xi = x - \frac{\beta(\lambda^2-4\mu)}{1-\delta(\lambda^2-4\mu)} t, \quad (3.14)$$
b) The two dimension Korteweg de Vries (2D KdV) equation

Consider the two dimensions Korteweg de Vries in the form, [11]

\[
(u_t - \epsilon u u_x + u_{xxx})_x + 3u_{yy} = 0, \tag{3.15}
\]

Put \( u(x, t) = u(\xi) \), \( \xi = x + \beta y - c t \), Eq. (3.15) become

\[
(3\beta^2 - c)u'' - \epsilon(u u')' + u'''' = 0, \tag{3.16}
\]

Integrating the above equation with respect to \( \xi \), we get

\[
(3\beta^2 - c)u - \frac{\epsilon}{2}u^2 + u'' = 0, \tag{3.17}
\]

Balancing \( u^2 \) with \( u'''' \) gives \( m = 2 \). thus the solution of Eq. (3.15) can be expressed by

\[
u(\xi) = a_0 + a_1 \left( \frac{G'(\xi)}{G(\xi)} \right) + a_2 \left( \frac{G''(\xi)}{G(\xi)} \right)^2, \tag{3.18}
\]

By solving this system we obtain \( a_0, a_1, a_2 \) and , we have two sets of solutions as

Case (1)

\[
a_0 = \frac{12\mu}{\epsilon}, \quad a_1 = \frac{12\lambda}{\epsilon}, \quad a_2 = \frac{12}{\epsilon}, \quad c = 3\beta^2 + \lambda^2 - 4\mu \tag{3.19}
\]

Case (2)

\[
a_0 = \frac{2(\lambda^2 + 2\mu)}{\epsilon}, \quad a_1 = \frac{12\lambda}{\epsilon}, \quad a_2 = \frac{12}{\epsilon}, \quad c = 3\beta^2 - \lambda^2 + 4\mu \tag{3.20}
\]

By using Eq.(34) and Eq(35), Eq.(33) can written as

\[
u_1(\xi) = \frac{12\mu}{\epsilon} + \frac{12\lambda}{\epsilon} \left( \frac{G'(\xi)}{G(\xi)} \right) + \frac{12}{\epsilon} \left( \frac{G''(\xi)}{G(\xi)} \right)^2, \tag{3.21}
\]

or

\[
u_2(\xi) = \frac{2(\lambda^2 + 2\mu)}{\epsilon} + \frac{12\lambda}{\epsilon} \left( \frac{G'(\xi)}{G(\xi)} \right) + \frac{12}{\epsilon} \left( \frac{G''(\xi)}{G(\xi)} \right)^2 \tag{3.22}
\]

With the knowledge of the solution of Eq.(5) and Eqs.(21-22), we have three types of travelling wave solutions of the Eq.(3.15) as

The first type: when \( \lambda^2 - 4\mu > 0 \),

\[
u_1(\xi) = -\frac{3(C_1^2 - C_2^2)(\lambda^2 - 4\mu)}{\epsilon(C_1 \cosh(\sqrt{\frac{\lambda^2 - 4\mu}{2}} - \xi) + C_2 \sinh(\sqrt{\frac{\lambda^2 - 4\mu}{2}} - \xi))^2}, \tag{3.23}
\]

Where \( \xi = x + \beta y - (3\beta^2 + \lambda^2 - 4\mu)t \), or

\[
u_2(\xi) = \frac{(\lambda^2 - 4\mu)}{\epsilon} \left( 2 - \frac{3(C_1^2 - C_2^2)}{(C_1 \cosh(\sqrt{\frac{\lambda^2 - 4\mu}{2}} - \xi) + C_2 \sinh(\sqrt{\frac{\lambda^2 - 4\mu}{2}} - \xi))^2} \right), \tag{3.24}
\]

Where \( \xi = x + \beta y - (3\beta^2 - \lambda^2 + 4\mu)t \)

The second type: when \( \lambda^2 - 4\mu < 0 \)
\[ u_3(\xi) = \frac{(\lambda^2-4\mu)(2 - \frac{3(C_1^2+C_2^2)}{(C_1\cos(\frac{1}{2}\sqrt{-\lambda^2+4\mu})+C_2\sin(\frac{1}{2}\sqrt{-\lambda^2+4\mu}))^2})}{\varepsilon}, \quad (3.25) \]

Where \( \xi = x + \beta y - (3\beta^2 + \lambda^2 - 4\mu)t, \) or

\[ u_4(\xi) = -\frac{3(C_1^2+C_2^2)(\lambda^2-4\mu)}{\varepsilon(C_1\cos(\frac{1}{2}\sqrt{-\lambda^2+4\mu})+C_2\sin(\frac{1}{2}\sqrt{-\lambda^2+4\mu}))^2}, \quad (3.26) \]

Where \( \xi = x + \beta y - (3\beta^2 - \lambda^2 + 4\mu)t \)

The Third type: when \( \lambda^2 - 4\mu = 0, \)

\[ u_5(\xi) = \frac{12c_2^2}{\varepsilon(c_2+c_2\xi)^2}, \quad (3.27) \]

Where \( \xi = x + \beta y - 3\beta^2t, \)

The behavior of the solutions \( u_3(x, t) \) and \( iu_3(x, t) \) for 2DKdV equation are shown in Figure(2)

**Figure 2**: \( C_1 = 2, C_2 = 4, \lambda = 3, \) and \( \mu = 1 \)

**IV. Conclusion**

In this work the \( (\frac{\partial}{\partial(\xi)}) \)-expansion method was applied successfully for solving some solitary wave equations in one and two dimensions. Two equations which are the IKdV and 2D KdV have been solved exactly. As a result, many exact solutions are obtained which include the hyperbolic functions, trigonometric functions and rational functions. It is worthwhile to mention that the proposed method is reliable and effective and gives more solutions. The method can also be efficiently used to construct new and more exact solutions for some other generalized nonlinear wave equations arising in mathematical physics.

**References**


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